



































































# Outline

- 1 Finite-state buffered machines
  - Intuitions and definitions
  - **Examples**
  - Different state arrangements
- 2 Some closure properties of FSBM Languages
  - Intersection with regular languages
  - Regular operations
  - Homomorphism and inverse homomorphism
- 3 Discussion and conclusion

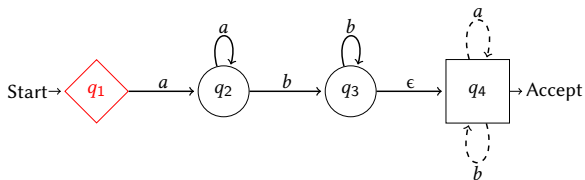








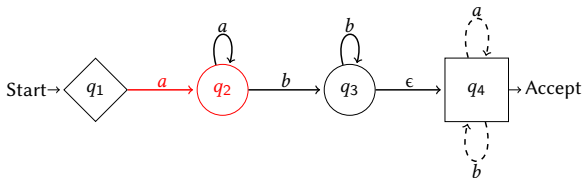
# An example run: abbabb



**Figure:** An FSBM  $M_2$  with  $G = \{q_1\}$  and  $H = \{q_4\}$ .  $L(M_2) = \{a^i b^j a^i b^j \mid i, j \geq 1\}$

input	state	buffer	mode
abbabb	$q_1$	$\epsilon$	N
abbabb	$q_1$	$\epsilon$	<b>B</b>

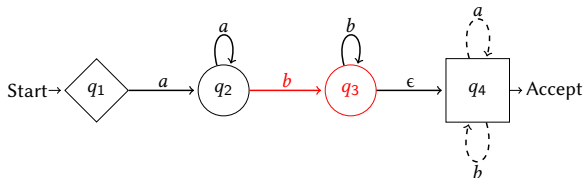
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input	state	buffer	mode
abbabb	$q_1$	$\epsilon$	N
abbabb	$q_1$	$\epsilon$	B
bbabb	$q_2$	<b>a</b>	B

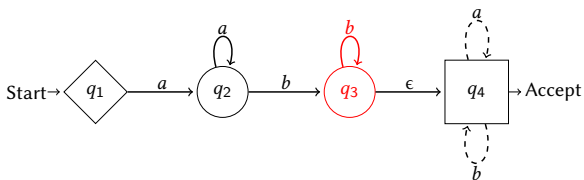
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input	state	buffer	mode
abbabb	$q_1$	$\epsilon$	N
abbabb	$q_1$	$\epsilon$	B
bbabb	$q_2$	a	B
babb	$q_3$	ab	B

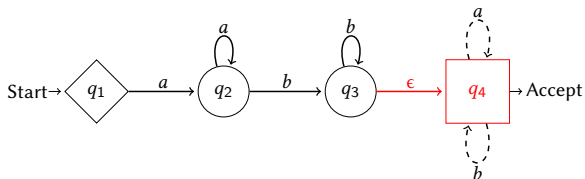
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input	state	buffer	mode
abbabb	$q_1$	$\epsilon$	N
abbabb	$q_1$	$\epsilon$	b
bbabb	$q_2$	a	B
babb	$q_3$	ab	B
abb	$q_3$	ab <b>b</b>	B

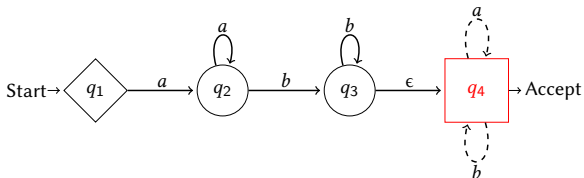
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input	state	buffer	mode
abbabb	$q_1$	$\epsilon$	N
abbabb	$q_1$	$\epsilon$	B
bbabb	$q_2$	a	B
babb	$q_3$	ab	B
abb	$q_3$	abb	B
abb	$q_4$	abb	B

# An example run: abbabb



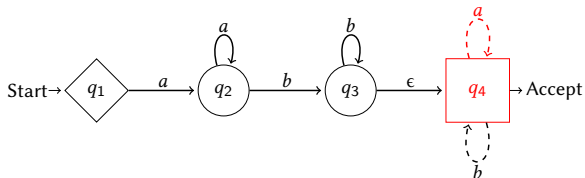
**Figure:** An FSM  $M_2$  with  $G = \{q_1\}$  and  $H = \{q_4\}$ .  $L(M_2) = \{a^i b^j a^i b^j \mid i, j \geq 1\}$

input	state	buffer	mode
abbabb	$q_1$	$\epsilon$	N
abbabb	$q_1$	$\epsilon$	B
bbabb	$q_2$	a	B
babb	$q_3$	ab	B
abb	$q_3$	abb	B
abb	$q_4$	abb	B

input	state	buffer	mode
abb	$q_4$	abb	<b>E</b>



# An example run: abbabb

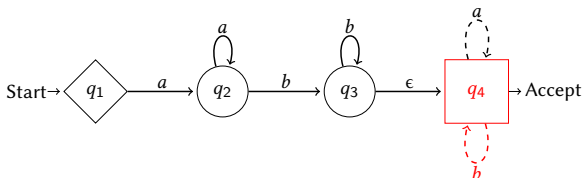


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input	state	buffer	mode
abbabb	$q_1$	$\epsilon$	N
abbabb	$q_1$	$\epsilon$	B
bbabb	$q_2$	a	B
babb	$q_3$	ab	B
abb	$q_3$	abb	B
abb	$q_4$	abb	B

input	state	buffer	mode
abb	$q_4$	abb	E
bb	$q_4$	bb	E

# An example run: abbabb

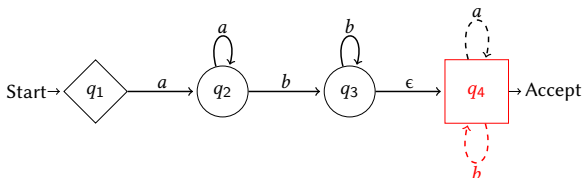


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input	state	buffer	mode
abbabb	$q_1$	$\epsilon$	N
abbabb	$q_1$	$\epsilon$	B
bbabb	$q_2$	a	B
babb	$q_3$	ab	B
abb	$q_3$	abb	B
abb	$q_4$	abb	B

input	state	buffer	mode
abb	$q_4$	abb	E
bb	$q_4$	bb	E
b	$q_4$	b	E

# An example run: abbabb

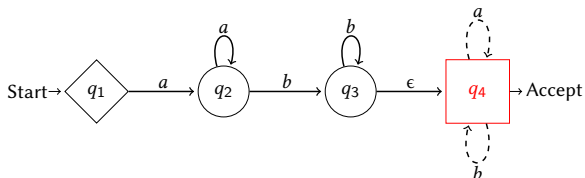


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input	state	buffer	mode
abbabb	$q_1$	$\epsilon$	N
abbabb	$q_1$	$\epsilon$	B
bbabb	$q_2$	a	B
babb	$q_3$	ab	B
abb	$q_3$	abb	B
abb	$q_4$	abb	B

input	state	buffer	mode
abb	$q_4$	abb	E
bb	$q_4$	bb	E
b	$q_4$	b	E
$\epsilon$	$q_4$	$\epsilon$	E

# An example run: abbabb

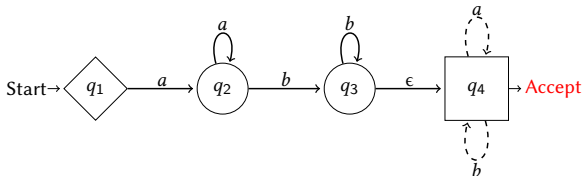


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input	state	buffer	mode
abbabb	$q_1$	$\epsilon$	N
abbabb	$q_1$	$\epsilon$	B
bbabb	$q_2$	a	B
babb	$q_3$	ab	B
abb	$q_3$	abb	B
abb	$q_4$	abb	B

input	state	buffer	mode
abb	$q_4$	abb	E
bb	$q_4$	bb	E
b	$q_4$	b	E
$\epsilon$	$q_4$	$\epsilon$	E
$\epsilon$	$q_4$	$\epsilon$	N

# An example run: abbabb



**Figure:** An FSBM  $M_2$  with  $G = \{q_1\}$  and  $H = \{q_4\}$ .  $L(M_2) = \{a^i b^j a^i b^j \mid i, j \geq 1\}$

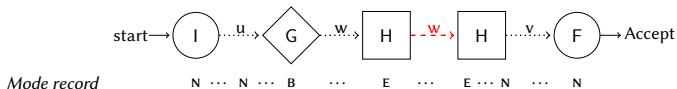
input	state	buffer	mode
abbabb	$q_1$	$\epsilon$	N
abbabb	$q_1$	$\epsilon$	B
bbabb	$q_2$	a	B
babb	$q_3$	ab	B
abb	$q_3$	abb	B
abb	$q_4$	abb	B

input	state	buffer	mode
abb	$q_4$	abb	E
bb	$q_4$	bb	E
b	$q_4$	b	E
$\epsilon$	$q_4$	$\epsilon$	E
$\epsilon$	$q_4$	$\epsilon$	N
ACCEPT			

# Outline

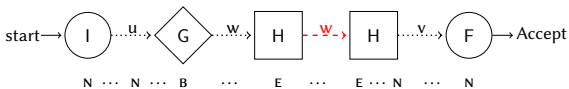
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# Different arrangements of G & H states

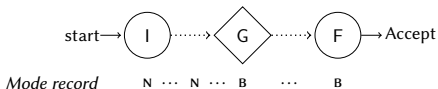


(a) Useful arrangements of G and H states

# Different arrangements of G & H states



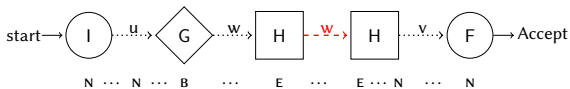
**(a) Useful arrangements of G and H states**



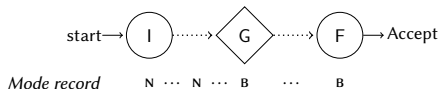
**(b) Non-Useful arrangements: No H states**



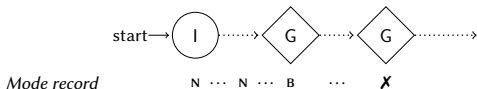
# Different arrangements of G & H states



(a) Useful arrangements of G and H states

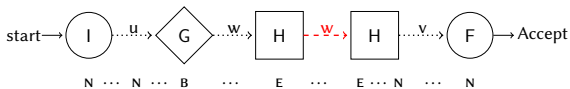


(b) Non-Useful arrangements: No H states

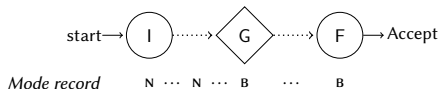


(c) Non-Useful arrangements: No H states in between two G states along a path

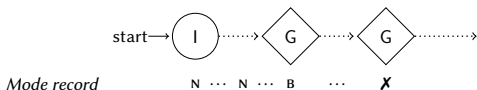
# Different arrangements of G & H states



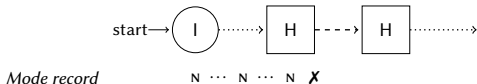
(a) Useful arrangements of G and H states



(b) Non-Useful arrangements: No H states



(c) Non-Useful arrangements: No H states in between two G states along a path



(d) Non-Useful arrangements: H states before G states



























# Thank you!





















































